# csv2bufr

Release 0.6.0

World Meteorological Organization (WMO)

2023-06-05

# TABLE OF CONTENTS:

1	Overview	3
2	Installation         2.1       Dependencies	<b>5</b> 5 5
3	Quick start         3.1       Command line interface         3.2       API	<b>7</b> 7 8
4	Anatomy of a BUFR4 message	11
5	BUFR4 Descriptors5.1Introduction5.2Format of BUFR descriptors5.3Replication / repetition5.4Scope of descriptors5.5Commonly used sequences5.6Further information	<b>13</b> 13 13 14 15 15 15
6	BUFR template mapping         6.1       input <short extended>DelayedDescriptorReplicationFactor         6.2       bufr_element         6.3       Units         6.4       Schema</short extended>	17 18 18 20 20
7	Examples7.1Data file (example-data.csv)7.2Creating a new mapping file7.3Customising the mapping file (bufr-mappings-edited.json)7.4Transformation	23 23 23 28 31
8	pygeoapi plugin8.1Overview8.2Installation8.3Usage	<b>33</b> 33 33 33
9	Development	35
10	Support	37

	License         11.1       Software         11.2       Documentation	
12	Indices and tables	45

### Author

World Meteorological Organization (WMO)

#### Contact

https://github.com/wmo-im/csv2bufr

#### Release

0.6.0

### Date

2023-06-05

### ONE

# **OVERVIEW**

The csv2bufr Python module contains both a Command Line Interface (CLI) and an API to convert data stored in a CSV file to the WMO BUFR data format. More information on the BUFR format can be found in the WMO Manual on Codes, Volume I.2

TWO

### INSTALLATION

### 2.1 Dependencies

The csv2bufr module relies on the ecCodes software library to perform the BUFR encoding. This needs to be installed prior to installing any of the Python packages, instructions can be found on the ecCodes documentation pages: https://confluence.ecmwf.int/display/ECC.

The following Python packages are required by the csv2bufr module:

• eccodes (NOTE: this is separate from the ecCodes library)

Additionally, the command line interface to csv2bufr requires:

• click

All the above packages can be installed by running:

pip install -r requirements.txt

### 2.2 Installation

#### 2.2.1 Docker

The quickest way to install and run the software is via a Docker image containing all the required libraries and Python modules:

docker pull wmoim/csv2bufr

This installs a Docker image based on Ubuntu and includes the ecCodes software library, dependencies noted above and the csv2bufr module (including the command line interface).

#### 2.2.2 Source

Alternatively, csv2bufr can be installed from source. First clone the repository and navigate to the cloned folder / directory:

```
git clone https://github.com/wmo-im/csv2bufr.git -b dev
cd csv2bufr
```

If running in a Docker environment, build the Docker image and run the container:

```
docker build -t csv2bufr .
docker run -it -v ${pwd}:/app csv2bufr
cd /app
```

The above step can be skipped if not using Docker. Now install the module and test:

```
python3 setup.py install
csv2bufr --help
```

The following output should be shown:

```
Usage: csv2bufr [OPTIONS] COMMAND [ARGS]...
csv2bufr
Options:
   --version Show the version and exit.
   --help Show this message and exit.
Commands:
   data data workflows
   mappings stored mappings
```

### THREE

# **QUICK START**

The csv2bufr Python module contains both a command line interface and an API to convert data stored in a CSV file to the WMO BUFR data format. For example, the command line interface reads in data from a CSV file, converts it to BUFR and writes out the data to the specified directory. e.g.:

```
csv2bufr data transform <my-csv-file.csv> \
    --bufr-template <csv-to-bufr-mapping.json> \
    --output <output-directory-path>
```

This command is explained in more detail below.

# 3.1 Command line interface

The following example transforms the data in file my-csv-file.csv to BUFR using template csv-to-bufr-mapping.json and writes the output to directory output-directory-path:

```
csv2bufr data transform <my-csv-file.csv> \
    --bufr-template <csv-to-bufr-mapping.json> \
    --output <output-directory-path>
```

The command is built on the Python Click module and is formed of three components (csv2bufr data transform), 1 arguments and 2 mandatory options (specified by –). The argument specifies the file to process of the data being processed. The options specify various configuration files to use.

- 1. my-csv-file.csv: argument specifying the CSV data file to process
- 2. --bufr-template csv-to-bufr-mapping.json: option followed by the bufr mapping template to use
- 3. --output-dir output-directory-path: option followed by output directory to write BUFR file to. The output filename is set using the md5 checksum of the BUFR data to ensure uniqueness, future versions will use the WIGOS ID and timestamp of the data to set the filename.

The output BUFR files can be validated using a tool such as the ECMWF BUFR validator.

### 3.1.1 Input CSV file

Currently, a single station per file is supported with each row treated as a separate record and one BUFR file per record created. The format of the input CSV file has a few requirements:

- A comma (i.e.,) must be used as the delimiter.
- Strings must be quoted.
- Missing values must be encoded as "None".
- The final row in the file must contain data and not be a new line.
- The timestamp of the records must be separated into components, i.e. year, month, day etc must each be in a separate column.
- The date/time elements should be in Universal Time Coordinated (UTC).
- The file must contain the WIGOS station identifier

### 3.1.2 WIGOS Station Identifier

Each station must have a WIGOS Station Identifier. More information can be found in the Guide to the WMO Integrated Observing System, section 2 (WMO-No. 1165).

### 3.1.3 BUFR mapping template (--bufr-template)

The mapping from CSV to BUFR is specified in a JSON file (see the BUFR template mapping page).

# 3.2 API

The command line interface uses the transform function from the csv2bufr module. This can be used directly, e.g.:

```
# import modules
import json
from csv2bufr import transform
# load data from file
with open("my-csv-file.csv") as fh:
   data = fh.read()
# load mapping
with open("csv-to-bufr-mapping.json") as fh:
   mapping = json.load(fh)
# call transform function
result = transform(data, mapping)
# iterate over items
for item in result:
    # get id and phenomenon time to use in output filename
   wsid = item["_meta"]["wigos_station_identifier"] # WIGOS station ID
    geometry = item["_meta"]["geometry"] # GeoJSON geometry object
```

```
timestamp = item["_meta"]["properties"]["datetime"] # phenomenonTime as datetime...

→ object

timestamp = timestamp.strftime("%Y%m%dT%H%MZ") # convert to string

# set filename

output_file = f"{wsid}_{timestamp}.bufr4"

# save to file

with open(output_file, "wb") as fh: # note binary write mode

fh.write(item["bufr4"])
```

The transform function returns an iterator that can be used to iterate over each line in the data file. Each item returned contains a dictionary with the following elements:

- item["bufr4"] binary BUFR data
- item["\_meta"] GeoJSON dictionary containing metadata elements
- item["\_meta"]["id"] identifier for result (set combination of wigos\_station\_identifier and datetime)
- item["\_meta"]["geometry"] GeoJSON geometry object of location of data
- item["\_meta"]["properties"] key/value pairs of properties/attributes
- item["\_meta"]["properties"]["md5"] the md5 checksum of the encoded BUFR data
- item["\_meta"]["properties"]["wigos\_station\_identifier"] WIGOS station identifier
- item["\_meta"]["properties"]["datetime"] characteristic date of data contained in result (from BUFR)
- item["\_meta"]["properties"]["originating\_centre"] originating centre for data (from BUFR)
- item["\_meta"]["properties"]["data\_category"] data category (from BUFR)

### ANATOMY OF A BUFR4 MESSAGE

In order to understand the mapping between a CSV file and its BUFR encoding it is first helpful to understand the anatomy of a BUFR message. A BUFR message is encoded in binary and contains 6 sections as shown in the diagram below. The ecCodes keys for the different elements are also shown as these are used to set certain elements (highlighted in red) as part of the conversion to BUFR. The non-highlighted elements (including those without an ecCodes key) are either set by the eccodes module based on the data, have a default value or can be omitted / set to missing.

The information cotained in Sections 0, 1, and 3 are essentially metadata specifying:

- the version of the BUFR tables used (editionNumber, masterTableNumber, masterTableVersionNumber);
- where the data have come from (bufrHeaderCentre, bufrHeaderSubCentre);
- the typical time of the observation (typicalYear ... typicalSecond);
- the type of data and what parameters are included (dataCategory, internationalDataSubCategory and unexpandedDescriptors).

These are all specified in the BUFR template mapping file.

The edition number and master table number should be 4 and 0 respectively. BUFR edition 4 is the latest version and whilst it is possible to define new BUFR tables for different application areas only Master Table 0 (MT0) has been defined (meteorology). The tables in MT0 are updated approximately every 6 months as part of the WMO fast track process and the authoritative source can be found in the WMO Manual on Codes, Volume I.2. Updates to this can be delayed and the latest version, including machine readable tables, can be found at https://github.com/wmo-im/BUFR4/ releases and it is recommended to use the the most recent release. The master branch contains the current working copy of the tables and is subject to change.

The BUFR header centre and bufr header sub centre are specified in Common Code Tables C-11 and C-12 respectively. The typical time of observation (typicalYear ... typicalSecond) should be determined based on the data to be encoded. Within the csv2bufr module and CLI only a single observation / weather report is encoded per file and so these should be set to those columns in the CSV specifying the year, month, day etc. More information is provided in the page on the BUFR template mapping (link to follow).

The data category should be set according to BUFR Table A, i.e. 0 for "Surface data - land" and 1 for "Surface data - sea". The international data sub category should be set according to Common Code Table C-13. The unexpanded descriptors specifies the data to be encoded in the data section is comprised of a list of the BUFR descriptors. These descriptors are detailed further on the next page (BUFR descriptors).

					_					
	/				Sect	ion 0 – Ir	ndicator section			
			ecCodes ke	y Len	igth (by	tes)	Description			
			4		The string "BUFR" in CCITT-IA5					
	totalLength	ı	3	Tota	al length of the BUFR message in byt	es				
	e	ditionNumb	er	1		BUFR edition number (4)				
4	, 				Section	n 1 – Ider	ntification section			
1	ecCode	s kev	Length (b	(tes)			Description			
	section11	•	3				Length of section 1			
	masterTabl	-	1		BUFR master table user (MT0)					
	bufrHeade		2		Ident	ification	of originating/generating centre (see C	,	able C-11)	
		bufrHeaderSubCentre				Identif	ication of originating/generating sub- ating/generating centre – see Common	entre (allocated	by	
	updateSeque	nceNumber	1	U	Update sequence number (zero for original messages and for messages contai delayed reports; incremented for the other updates)					
	section1	Flags	1			Fl	ag indicating presence of optional sec	tion (section 2)		
	dataCat	egory	1				Data category (Table A)			
	internationalDat		1		Inte	rnational	data sub-category (see Common Cod		d Note 3)	
	dataSubC	ategory	1			Lo	ocal data sub-category (defined locally data-processing (ADP) centres – se			
	masterTablesVe	ersionNumber	1		BUF	R master	table version number (see Common C	Code Table C–0 a	nd Note 2)	
	localTablesVer	rsionNumber	1		Versi	on numbe	er of local tables used to augment mas	ter table in use –	see Note 2	
	typical	Year	2				Typical year of BUFR message	contents		
	typicalM	Aonth	1				Typical month of BUFR message	contents		
	typical	IDay	1				contents			
	typical	Hour	1		Typical hour of BUFR message contents					
	typicalM	/linute	1		Typical minute of BUFR message contents					
	econd	1		Typical second of BUFR message			contents			
			0+		Optional data – for local use by ADP			OP centres		
BUFR4 message					Faat	ion 2 C	Intional caption			
Section 0			ecCodes		Length (bytes)		Description			
Section 1			cecodes	xcy Lt	3 angun (0	ytes)	Length of section if present			
Section 2				1		Set to zero				
Section 3							served for local use by ADP centres			
Section 4										
Section 5					Section	3 – Data	description section			
		ecCodes	key	Length (	(bytes)		Description			
		section3L	ength	3			length of section			
				1		Set to zero				
		numberOfS	ubsets	2	2		Number of data subsets			
	section3F	lags	1	1		Flags used to indicate compressed and of				
V	unexpandedDe	Descriptors		2+ List		ist of data descriptors describing data contained in section e.g. [301150, 307080])				
					S	ection 4-	Data section			
		ecCodes k		ey Length (byt		bytes) Description				
			ecCo	des key	Lengt	th (bytes) Description				
						3	Length of section 4			
						1	Set to zero			
							Binary string of encoded data.			
					<b>C</b> .	action 5	End section	1		
			ecCodes k	V Len	gth (byt		- End section Description			
			cecoues K	J Len	4		string "7777" encode in CCITT IA-5	-		
					,	inc				

# **BUFR4 DESCRIPTORS**

# 5.1 Introduction

As part of the BUFR format, a list of the included parameters is embedded within the file using the unexpandedDescriptors element of Section 3. This element takes a list of the parameters to be included and the order of those parameters. For example, the unexpanded descriptor list (in text, see format of descriptors below):

```
["unexpandedDescriptors"] = ["wigosID", "year", "month", "day", "hour", "minute", \
"latitude", "longitude", "pressure reduced to mean sea...
→level"]
```

would specify that the station identifier (wigosID) followed by the date, time, location and then the pressure reduced to mean sea level would be included in the data section. For conciseness, aliases (or sequences in BUFR terminology) exist to group commonly reported parameters together, for example grouping the year, month and day together in the group date. Using sequences, the above example becomes:

```
["unexpandedDescriptors"] = ["wigosID", "date", "time", "location", "pressure reduced to_

→mean sea level"]
```

where

```
["date"] = ["year", "month", "day"]
["time"] = ["hour", "minute"]
["location"] = ["latitude", "longitude"]
```

These sequences form building blocks that can be used to create much longer sequences using a small number of descriptors.

# 5.2 Format of BUFR descriptors

Whilst text strings have been used above to represent the parameters to report this has been done for ease of reading and explanation. Within the BUFR format these are specified by 6 digit codes of the form FXXYYY, with each of F, XX and YYY having specific meaning.

- F: Type of BUFR descriptor
  - 0: element descriptor (BUFR Table B);
  - 1: replication (or repetition) descriptor;
  - 2: operator (BUFR Table C);
  - 3: sequence descriptor (BUFR Table D)

- XX: Sub-table (class) within type of descriptor
- YYY: Index within in sub-table.

As an example, the table below shows the first few entries from BUFR Table B 01.

For the above example, using the FXXYYY notation, the list of abbreviated (or unexpanded) descriptors becomes:

["unexpandedDescriptors"] = [301150, 301011, 301012, 301023, 010051]

where:

### 5.3 Replication / repetition

Within the BUFR format, elements can be repeated using the replication descriptors (F=1 in FXXYYY). For example, we may want to repeat temperature and humidity measurements as part of an atmospheric profile or, alternatively, the daily minimum and maximum temperatures within a month. In some cases we may know the number of repetitions before encoding and all data of the same type may have the same number of repetitions. In this case the number of replications can be set before hand and included in the sequence. In other cases, there may be a variable number of repetitions and so the number is set at the time of encoding.

When using the replication descriptor (1XXYYY), the XX component indicates the number of following descriptors to repeat and the YYY component the number of replications. For example, to repeat the day of month, maximum and minimum temperatures 5 times we would use:

	repeat (1) next 3 (03) descriptors 5 (005) times	s descriptors to be repeated
[unexpandedDescriptors] =	103005	,004003,012016,012017
[unexpandedDescriptors] =		,004003,012010,012017
	FXXYYY	

In expanded form, or without using the replication, this would be equivalent to:

[expandedDescriptors]	=	004003, 012016, 012017,	(5.1	)
-----------------------	---	-------------------------	------	---

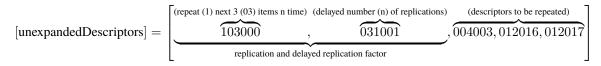
004000 010010 010017	(5.0)
004003, 012016, 012017,	(5.2)

```
004003, 012016, 012017, (5.3)
```

```
004003, 012016, 012017, (5.4)
```

```
004003, 012016, 012017 (5.5)
```

If we do not known the number of replications, or there can be a variable number of replications, for a given sequence of descriptors we can set the YYY element (number of replications) to zero and follow the replication descriptor with a delayed replication factor.



This works in the same way as the regular replication except that the number of replications (n) is set at the the time of encoding and included in data. Often, within sequences, delayed descriptors are used to specify optional elements using the short delayed descriptor replication factor (031000) that takes a value of either 0 or 1.

Within the csv2bufr module the number of delayed replications needs to be set within the mapping file using the inputDelayedDescriptorReplicationFactor key. More information is provided on the mappings page.

### 5.4 Scope of descriptors

BUFR Table B descriptors within classes 0 - 8 contain metadata about the observations. For example, the location of an observations, the instrumentation used to make an observation or the time period over which an observation was made or averaged. These descriptors remain in force and apply to all subsequent elements until they are either reused or set to missing. For example the sequence [007032, 012001, 007032, 012001, 007032] could be used to record air temperature measurements at two different heights, e.g.:

```
# set height of sensor for following observations
[007032] = ["heightOfSensorAboveLocalGroundOrDeckOfMarinePlatform"] = 2.0
[012001] = ["airTemperature"] = 280.15 # air temperature at 2 m height
# redefine height of sensor to 10 m
[007032] = ["heightOfSensorAboveLocalGroundOrDeckOfMarinePlatform"] = 10.0
[012001] = ["airTemperature"] = 280.07 # air temperature at 10 m height
# cancel height of sensor, following observations will have an undefined height
[007032] = ["heightOfSensorAboveLocalGroundOrDeckOfMarinePlatform"] = None
```

### 5.5 Commonly used sequences

Listed below are some commonly used sequences:

- 307080: Sequence for representation of synoptic reports from a fixed land station suitable for SYNOP data.
- 315008: Sequence for the representation of data from moored buoys.
- 315009: Sequence for the representation of data from drifting buoys.
- As this documentation is developed further additional examples will be added.

### 5.6 Further information

The description of the BUFR operators (F = 2 in the FXXYYY notation) is beyond the scope of this documentation. For users wanting to define new sequences, including the use of the operators, it is recommended to refer to Volume I.2 of the WMO Manual on Codes. However, before defining a new sequence it is recommended to check if any of the existing sequence meet the user requirements. See the *support page* for information on how to get further information and support.

### **BUFR TEMPLATE MAPPING**

The mapping between the input CSV data and the output BUFR data is specified in a JSON file. The csv2bufr module validates the mapping file against the schema shown at the bottom of this page prior to attempted the transformation to BUFR. This schema specifies 7 primary properties all of which are mandatory:

- inputDelayedDescriptorReplicationFactor array of integers, values for the delayed descriptor replication factors to use
- inputShortDelayedDescriptorReplicationFactor array of integers, values for the short delayed descriptor replication factors to use
- inputExtendedDelayedDescriptorReplicationFactor array of integers, values for the extended delayed descriptor replication factors to use
- number\_header\_rows integer, the number of header rows in the file before the first data, including the row with column names.
- column\_names\_row integer, the row number that gives the column names.
- wigos\_station\_identifier either constant WIGOS station identifier (e.g. const:0-20000-0-123) or column from csv data file containing the WSI (e.g. data:WSI\_column).
- header array of objects (see below), header section containing metadata
- data array of object (see below) section mapping from the CSV columns to the BUFR elements

The header and data sections contain arrays of bufr\_element objects mapping to either the different fields in the header sections of the BUFR message or to the data section respectively. More information is provided below. In both cases the field eccodes\_key from the bufr\_element object is used to indicate the BUFR element mapped rather than the 6 digit BUFR FXXYYY code. The field value specifies where the data to encode comes from. This can be one of the following:

- data: this specifies that the data should come from the data file.
- const: this specifies that a constant value should be used

For example, the code block below shows how the pressure reduced to mean sea level would be mapped from the column "mslp" in the CSV file to the BUFR element indicated by the eccodes key "pressureReducedToMeanSeaLevel" (FXXYYY = 010051).

```
{
    "data":[
        {"eccodes_key": "pressureReducedToMeanSeaLevel", "value": "data:mslp"}
]
}
```

The code block below gives examples for both constant values and a value read from the data file:

```
{
    "header":[
        {"eccodes_key": "dataCategory", "value": "const:0"}
],
    "data":[
        {"eccodes_key": "latitude", "value": "const:46.2234923"},
        {"eccodes_key": "longitude", "value": "const:6.1475485"},
        {"eccodes_key": "pressureReducedToMeanSeaLevel", "value": "data:mslp"},
]
}
```

In this example, the dataCategory field in BUFR section 1 (see *Anatomy of a BUFR4 message*) is mapped to the constant value 0; the latitude and longitude to the value specified; and the pressureReducedToMeanSeaLevel to the data from the "mslp" column in the CSV file.

The keys used for the header elements are listed on the *Anatomy of a BUFR4 message* page, with the mandatory keys highlighted in red. The list of keys can also be found at:

• https://confluence.ecmwf.int/display/ECC/BUFR+headers

Similarly the keys for the different data elements can be found at:

• https://confluence.ecmwf.int/display/ECC/WMO%3D37+element+table

# 6.1 input<Short|Extended>DelayedDescriptorReplicationFactor

Due to the way that eccodes works any delayed replication factors need to be specified before encoding and included in the mapping file. This currently limits the use of the delayed replication factors to static values for a given mapping. For example every data file that uses a given mapping file has the same optional elements present or the same number of levels in an atmospheric profile present.

For sequences that do not include delayed replications the inputDelayedDescriptorReplicationFactor etc must still be included but may be set to an empty array. e.g.

```
"inputDelayedDescriptorReplicationFactor": [],
"inputShortDelayedDescriptorReplicationFactor": []
"inputExtendedDelayedDescriptorReplicationFactor": []
```

# 6.2 bufr\_element

Each item in the header and data arrays of the mapping template must conform with the definition of the bufr\_element object specified in the schema shown below. This object contains an eccodes\_key field specifying the BUFR element the data are being mapped to as described above and up to 3 others pieces of information:

- the source of the data (value)
- valid range information (valid\_min, valid\_max)
- simple scaling and offset parameters (scale, offset)

Only one source can be mapped, if multiple sources are specified the validation of the mapping file by csv2bufr will fail. As noted at the start of this page. the value field maps the data to one of:

{

}

- data: this specifies that the data should come from the data file
- const: this specifies that a constant value should be used

and takes the form "value": "<keyword>:<column|value>" where <keyword> is the string data or const. <column|value> can specify either the column name from the data file or it can specify a constant value to use.

The valid\_min and valid\_max are optional and can be used to perform a basic quality control of numeric fields. The values to use are specified in the same way as for the value element, with the values coming from either a constant value or from the data file. If these fields are specified the csv2bufr module checks the value extracted from the source to the indicated valid minimum and maximum values. If outside of the range the value is set to missing. This check is applied before any scaling of the data.

The scale and offset fields are conditionally optional, either both can be omitted or both can included. Including only one will result in a failed validation of the mapping file. These allow simple unit conversions to be performed, for example from degrees Celsius to Kelvin or from hectopascals to Pascals. Again, the values are specified in the same way as for the other fields. The scaled values are calculated as:

scaled\_value = value  $\times 10^{\text{scale}} + \text{offset}$ 

The scaled value is then used to set the indicated BUFR element. For example:

```
{
    "data":[
        {
            "eccodes_key": "pressureReducedToMeanSeaLevel",
            "value": "data:mslp",
            "scale": "const:2",
            "offset": "const:0"
        }
]
```

Would convert the value contained in the "mslp" column of the CSV file from hPa to Pa by multiplying by 100 and adding 0.

For each of the above elements (value, valid\_min, valid\_max, scale, offset) null values must be excluded from the mapping file.

An individual BUFR descriptor can occur multiple times within a single BUFR message. To allow the indexing of the descriptors within a particular message, and the inclusions of multiple descriptors or keys with the same name, eccodes prepends an index number to the eccodes\_key. For the first occurrence the index number can be omitted but for all other cases it should be included. The index is indicated within the eccodes\_key using #index#eccodes\_key, an example is given below.

```
{
    "data":[
        {
            "#1#eccodes_key": "pressureReducedToMeanSeaLevel",
                "csv_column": "data:mslp",
                "scale": "const:2",
                "offset": "const:0"
        }
]
}
```

# 6.3 Units

It should be noted that the units of the data to be encoded into BUFR should match those specified in BUFR table B (e.g. see https://confluence.ecmwf.int/display/ECC/WMO%3D37+element+table), i.e. Kelvin for temperatures, Pascals for pressure etc. Simple conversions between units are possible as specified above using the scale and offset fields. Some additional examples are given below.

```
{
    "data":[
        {
            "eccodes_key": "airTemperature",
            "value": "data:AT-fahrenheiht",
            "scale": "const:-0.25527",
            "offset": "const:459.67"
        },
        {
            "eccodes_key": "airTemperature",
            "value": "data:AT-celsius",
            "scale": "const:0",
            "offset": "const:273.15"
        },
        {
            "eccodes_key": "pressure",
            "value": "data:pressure-hPa",
            "scale": "const:2",
            "offset": "const:0"
        }
    ]
}
```

# 6.4 Schema

```
{
   "$id": "csv2bufr.wis2.0.node.wis",
   "$schema": "https://json-schema.org/draft/2020-12/schema",
   "type": "object".
    "properties": {
        "inputShortDelayedDescriptorReplicationFactor": {
            "type": "array",
            "items": {"type": "integer"}
        },
        "inputDelayedDescriptorReplicationFactor": {
            "type": "array",
            "items": {"type": "integer"}
        },
        "inputExtendedDelayedDescriptorReplicationFactor": {
            "type": "array",
            "items": {"type": "integer"}
        },
        "number_header_rows": {
```

```
(continued from previous page)
```

```
"type": "integer",
           "description": "Number of header rows in file before the data"
       },
        "column_names_row": {
           "type": "integer",
           "description": "Which header line the column names is given on"
       },
        "wigos_station_identifier": {
            "type": "string",
           "description": "Either the WIGOS station identifier for the data or the.
⇔column in the CSV file containing the identifier"
       },
       "delimiter": {
           "type": "string",
           "description": "The delimiter used to separate fields in the input csv file,
→must be one of ',', ';'. '|' or [tab]"
       },
        "quoting": {
           "type": "string",
           "description": "CSV quoting method to use, must be one of QUOTE_NONNUMERIC,
↔QUOTE_ALL, QUOTE_MINIMAL or QUOTE_NONE"
       },
       "quotechar": {
           "type": "string",
           "description": "quote character to use, e.g. \", ' etc"
       },
       "header":{
           "type": "array",
           "items": {"$ref": "#/$defs/bufr_element"},
           "description": "Contents of header sections of BUFR message"
       },
       "data": {
           "type": "array",
           "items": {"$ref": "#/$defs/bufr_element"},
           "description": "mapping from CSV file (or metadata json file) to BUFR"
       }
   },
   "required" : [
       "inputShortDelayedDescriptorReplicationFactor",
       "inputDelayedDescriptorReplicationFactor",
       "inputExtendedDelayedDescriptorReplicationFactor",
       "column_names_row", "number_header_rows", "header", "data"],
   "$defs":{
       "bufr_element": {
           "type": "object",
           "properties": {
                "eccodes_key": {
                    "type": "string",
                    "descripition": "eccodes key used to set the value in the BUFR data"
                },
```

```
"value": {
                     "type": [
                         "string"
                     ],
                     "description": "where to extract the value from, can be one off 'data
\rightarrow','metadata','const','array' followed by the value or column header"
                 },
                 "valid_min": {
                     "type": "string",
                     "description": "Minimum valid value for parameter if set"
                },
                 "valid_max": {
                     "type": "string",
                     "description": "Maximum value for for the parameter if set"
                },
                 "scale": {
                     "type": "string",
                     "description": "Value used to scale the data by before encoding_
\hookrightarrowusing the same conventions as in BUFR"
                },
                 "offset": {
                     "type": "string",
                     "description": "Value added to the data before encoding to BUFR_
\rightarrow following the same conventions as BUFR"
                }
            },
            "required": ["eccodes_key", "value"],
            "all0f": [
                 {
                     "dependentRequired": {"scale": ["offset"]}
                },
                 {
                     "dependentRequired": {"offset": ["scale"]}
                 }
            ]
        }
    }
}
```

### SEVEN

### **EXAMPLES**

This page follows through a worked example:

- 1. Example data file
- 2. Creating a new mapping file
- 3. Editing the mapping file
- 4. Running the transformation

All the example files used are downloadable at the end of this page.

# 7.1 Data file (example-data.csv)

Table 1: example-data.csv

wsi	year	month	day	hour	minute	lati-	longi-	slp	mslp	ppp	а	brmh
						tude	tude					
0-20000-0-	2022	02	10	6	0	46.2475	6.12774	978.3	1029.90	-	8	412.3
06700										0.4		

# 7.2 Creating a new mapping file

A command line tool to create an empty BUFR mapping template has been included as part of the csv2bufr module. This can be invoked using the csv2bufr mappings create <BUFR descriptors> command. E.g.:

```
csv2bufr mappings create 301150 301011 301012 301021 007031 302001 --output bufr-

→mappings.json
```

generates the following file:

```
{
    "inputDelayedDescriptorReplicationFactor": [],
    "inputShortDelayedDescriptorReplicationFactor": [],
    "inputExtendedDelayedDescriptorReplicationFactor": [],
    "wigos_station_identifier": "data:wsi",
    "number_header_rows": 1,
    "column_names_row": 1,
    "header": [
        {
        }
        }
    }
}
```

```
"eccodes_key": "edition",
    "value": ""
},
{
    "eccodes_key": "masterTableNumber",
    "value": ""
},
{
    "eccodes_key": "bufrHeaderCentre",
    "value": ""
},
{
    "eccodes_key": "bufrHeaderSubCentre",
    "value": ""
},
{
    "eccodes_key": "updateSequenceNumber",
    "value": ""
},
{
    "eccodes_key": "dataCategory",
    "value": ""
},
{
    "eccodes_key": "internationalDataSubCategory",
    "value": ""
},
{
    "eccodes_key": "dataSubCategory",
    "value": ""
},
{
    "eccodes_key": "masterTablesVersionNumber",
    "value": ""
},
{
    "eccodes_key": "localTablesVersionNumber",
    "value": ""
},
{
    "eccodes_key": "typicalYear",
    "value": ""
},
{
    "eccodes_key": "typicalMonth",
    "value": ""
},
{
    "eccodes_key": "typicalDay",
    "value": ""
},
{
```

```
"eccodes_key": "typicalHour",
        "value": ""
    },
    {
        "eccodes_key": "typicalMinute",
        "value": ""
    },
    {
        "eccodes_key": "typicalSecond",
        "value": ""
    },
    {
        "eccodes_key": "typicalDate",
        "value": ""
    },
    {
        "eccodes_key": "typicalTime",
        "value": ""
    },
    {
        "eccodes_key": "numberOfSubsets",
        "value": ""
    },
    {
        "eccodes_key": "observedData",
        "value": ""
    },
    {
        "eccodes_key": "compressedData",
        "value": ""
    },
    {
        "eccodes_key": "unexpandedDescriptors",
        "value": "array: 301150, 301011, 301012, 301021, 7031, 302001"
    },
    {
        "eccodes_key": "subsetNumber",
        "value": ""
    }
],
"data": [
    {
        "eccodes_key": "#1#wigosIdentifierSeries",
        "value": "",
        "valid_min": "const:0",
        "valid_max": "const:14",
        "scale": "const:0",
        "offset": "const:0"
    },
    {
        "eccodes_key": "#1#wigosIssuerOfIdentifier",
        "value": "",
```

```
(continued from previous page)
```

```
"valid_min": "const:0",
    "valid_max": "const:65534",
    "scale": "const:0",
    "offset": "const:0"
},
{
    "eccodes_key": "#1#wigosIssueNumber",
    "value": "",
    "valid_min": "const:0",
    "valid_max": "const:65534",
    "scale": "const:0",
    "offset": "const:0"
},
{
    "eccodes_key": "#1#wigosLocalIdentifierCharacter",
    "value": ""
},
{
    "eccodes_key": "#1#year",
    "value": "",
    "valid_min": "const:0",
    "valid_max": "const:4094",
    "scale": "const:0",
    "offset": "const:0"
},
{
    "eccodes_key": "#1#month",
    "value": "",
    "valid_min": "const:0",
    "valid_max": "const:14",
    "scale": "const:0",
    "offset": "const:0"
},
{
    "eccodes_key": "#1#day",
    "value": "",
    "valid_min": "const:0",
    "valid_max": "const:62",
    "scale": "const:0",
    "offset": "const:0"
},
{
    "eccodes_key": "#1#hour",
    "value": "",
    "valid_min": "const:0",
    "valid_max": "const:30",
    "scale": "const:0",
    "offset": "const:0"
},
{
    "eccodes_key": "#1#minute",
    "value": "",
```

```
"valid_min": "const:0",
    "valid_max": "const:62",
    "scale": "const:0",
    "offset": "const:0"
},
{
    "eccodes_key": "#1#latitude",
    "value": "".
    "valid_min": "const:-90.0",
    "valid_max": "const:245.5443",
    "scale": "const:0",
    "offset": "const:0"
},
{
    "eccodes_key": "#1#longitude",
    "value": "",
    "valid_min": "const:-180.0",
    "valid_max": "const:491.08862",
    "scale": "const:0",
    "offset": "const:0"
},
{
    "eccodes_key": "#1#heightOfBarometerAboveMeanSeaLevel",
    "value": "",
    "valid_min": "const:-400.0",
    "valid_max": "const:12707.0",
    "scale": "const:0".
    "offset": "const:0"
},
{
    "eccodes_key": "#1#nonCoordinatePressure",
    "value": "",
    "valid_min": "const:0",
    "valid_max": "const:163820",
    "scale": "const:0",
    "offset": "const:0"
},
{
    "eccodes_key": "#1#pressureReducedToMeanSeaLevel".
    "value": "",
    "valid_min": "const:0",
    "valid_max": "const:163820",
    "scale": "const:0",
    "offset": "const:0"
},
{
    "eccodes_key": "#1#3HourPressureChange",
    "value": "",
    "valid_min": "const:-5000",
    "valid_max": "const:5220",
    "scale": "const:0",
    "offset": "const:0"
```

This file includes the representable range (valid\_min and valid\_max) for the different BUFR elements. These should be set to the physical range where applicable.

# 7.3 Customising the mapping file (bufr-mappings-edited.json)

Editing the bufr mappings file to map to the above example CSV data we have:

```
{
    "inputDelayedDescriptorReplicationFactor": [],
   "inputShortDelayedDescriptorReplicationFactor": [],
    "inputExtendedDelayedDescriptorReplicationFactor": [],
    "wigos_station_identifier": "data:wsi",
    "number_header_rows": 1,
   "column_names_row": 1,
    "header": [
        {
            "eccodes_key": "edition",
            "value": "const:4"
        },
        {
            "eccodes_key": "masterTableNumber",
            "value": "const:0"
        },
        {
            "eccodes_key": "updateSequenceNumber",
            "value": "const:0"
        },
        {
            "eccodes_key": "dataCategory",
            "value": "const:0"
        },
        {
            "eccodes_key": "internationalDataSubCategory",
            "value": "const:6"
        },
        {
            "eccodes_key": "masterTablesVersionNumber",
            "value": "const:36"
```

```
},
    {
        "eccodes_key": "typicalYear",
        "value": "data:year"
    },
    {
        "eccodes_key": "typicalMonth",
        "value": "data:month"
    },
    {
        "eccodes_key": "typicalDay",
        "value": "data:day"
    },
    {
        "eccodes_key": "typicalHour",
        "value": "data:hour"
    },
    {
        "eccodes_key": "typicalMinute",
        "value": "data:minute"
    },
    {
        "eccodes_key": "numberOfSubsets",
        "value": "const:1"
    },
    {
        "eccodes_key": "observedData",
        "value": "const:1"
    },
    {
        "eccodes_key": "compressedData",
        "value": "const:0"
    },
    {
        "eccodes_key": "unexpandedDescriptors",
        "value": "array: 301150, 301011, 301012, 301021, 7031, 302001"
    }
],
"data": [
    {
        "eccodes_key": "#1#wigosIdentifierSeries",
        "value": "metadata:wsi_series",
        "valid_min": "const:0",
        "valid_max": "const:0"
    },
    {
        "eccodes_key": "#1#wigosIssuerOfIdentifier",
        "value": "metadata:wsi_issuer",
        "valid_min": "const:0",
        "valid max": "const:65534"
    },
    {
```

```
"eccodes_key": "#1#wigosIssueNumber",
    "value": "metadata:wsi_issue_number",
    "valid_min": "const:0",
    "valid_max": "const:65534"
},
{
    "eccodes_key": "#1#wigosLocalIdentifierCharacter",
    "value": "metadata:wsi_local"
},
{
    "eccodes_key": "#1#year",
    "value": "data:year",
    "valid_min": "const:2022",
    "valid_max": "const:2025"
},
{
    "eccodes_key": "#1#month",
    "value": "data:month",
    "valid_min": "const:1",
    "valid_max": "const:12"
},
{
    "eccodes_key": "#1#day",
    "value": "data:day",
    "valid_min": "const:1"
    "valid_max": "const:31"
},
{
    "eccodes_key": "#1#hour",
    "value": "data:hour",
    "valid_min": "const:0",
    "valid max": "const:23"
},
{
    "eccodes_key": "#1#minute",
    "value": "data:minute",
    "valid_min": "const:0",
    "valid_max": "const:59"
},
{
    "eccodes_key": "#1#latitude",
    "value": "data:latitude",
    "valid_min": "const:-90.0",
    "valid_max": "const:90.0"
},
{
    "eccodes_key": "#1#longitude",
    "value": "data:longitude",
    "valid_min": "const:-180.0",
    "valid max": "const:180.0"
},
{
```

```
"eccodes_key": "#1#heightOfBarometerAboveMeanSeaLevel",
            "value": "data:brmh",
            "valid_min": "const:-400.0",
            "valid_max": "const:12707.0"
        },
        {
            "eccodes_key": "#1#nonCoordinatePressure",
            "value": "data:slp",
            "valid_min": "const:0",
            "valid_max": "const:163820",
            "scale": "const:2",
            "offset": "const:0"
        },
        {
            "eccodes_key": "#1#pressureReducedToMeanSeaLevel",
            "value": "data:mslp",
            "valid_min": "const:0"
            "valid_max": "const:163820",
            "scale": "const:2",
            "offset": "const:0"
        },
        {
            "eccodes_key": "#1#3HourPressureChange",
            "value": "data:ppp",
            "valid_min": "const:-5000",
            "valid_max": "const:5220",
            "scale": "const:2".
            "offset": "const:0"
        },
        {
            "eccodes_key": "#1#characteristicOfPressureTendency",
            "value": "data:a",
            "valid_min": "const:0",
            "valid_max": "const:14"
        }
    ]
}
```

Note that the sequence includes no delayed replications and so the inputDelayedDescriptorReplicationFactor etc can be left as empty arrays. Elements that would be set to null have been removed.

# 7.4 Transformation

```
csv2bufr data transform \
    ./example-data.csv \
    --bufr-template ./bufr-mappings-edited.json \
    --output-dir ./
```

The links below can be used to download the example files:

```
    example-data.csv
```

- bufr-mappings-edited.json
- example output (d0464c97a88ea99f119e87629844c5dd.bufr4)

#### EIGHT

## **PYGEOAPI PLUGIN**

## 8.1 Overview

csv2bufr also provides a custom [pygeoapi](https://pygeoapi.io) processing plugin, providing csv2bufr functionality via OGC API - Processes.

## 8.2 Installation

To integrate this plugin in pygeoapi:

- ensure csv2bufr and its dependencies are installed into the pygeoapi deployment environment
- add the processes to the pygeoapi configuration as follows:

```
csv2bufr-transform:
    type: process
    processor:
        name: csv2bufr.pygeoapi_plugin.csv2bufrProcessor
```

• regenerate the pygeoapi OpenAPI configuration

pygeoapi openapi generate \$PYGEOAPI\_CONFIG --output-file \$PYGEOAPI\_OPENAPI

• restart pygeoapi

## 8.3 Usage

The resulting processes will be available at the following endpoints:

/processes/csv2bufr-transform

Note that pygeoapi's OpenAPI/Swagger interface (at /openapi) also provides a developer-friendly interface to test and run requests

# NINE

## DEVELOPMENT

See discussion board and issues on GitHub:

- Discussion board
- Issues

## TEN

## SUPPORT

See discussion board and issues on GitHub:

- Discussion board
- Issues

#### ELEVEN

#### LICENSE

#### 11.1 Software

Apache License Version 2.0, January 2004 http://www.apache.org/licenses/ TERMS AND CONDITIONS FOR USE, REPRODUCTION, AND DISTRIBUTION 1. Definitions. "License" shall mean the terms and conditions for use, reproduction, and distribution as defined by Sections 1 through 9 of this document.

"Licensor" shall mean the copyright owner or entity authorized by the copyright owner that is granting the License.

"Legal Entity" shall mean the union of the acting entity and all other entities that control, are controlled by, or are under common control with that entity. For the purposes of this definition, "control" means (i) the power, direct or indirect, to cause the direction or management of such entity, whether by contract or otherwise, or (ii) ownership of fifty percent (50%) or more of the outstanding shares, or (iii) beneficial ownership of such entity.

"You" (or "Your") shall mean an individual or Legal Entity exercising permissions granted by this License.

"Source" form shall mean the preferred form for making modifications, including but not limited to software source code, documentation source, and configuration files.

"Object" form shall mean any form resulting from mechanical transformation or translation of a Source form, including but not limited to compiled object code, generated documentation, and conversions to other media types.

"Work" shall mean the work of authorship, whether in Source or Object form, made available under the License, as indicated by a

copyright notice that is included in or attached to the work (an example is provided in the Appendix below).

"Derivative Works" shall mean any work, whether in Source or Object form, that is based on (or derived from) the Work and for which the editorial revisions, annotations, elaborations, or other modifications represent, as a whole, an original work of authorship. For the purposes of this License, Derivative Works shall not include works that remain separable from, or merely link (or bind by name) to the interfaces of, the Work and Derivative Works thereof.

"Contribution" shall mean any work of authorship, including the original version of the Work and any modifications or additions to that Work or Derivative Works thereof, that is intentionally submitted to Licensor for inclusion in the Work by the copyright owner or by an individual or Legal Entity authorized to submit on behalf of the copyright owner. For the purposes of this definition, "submitted" means any form of electronic, verbal, or written communication sent to the Licensor or its representatives, including but not limited to communication on electronic mailing lists, source code control systems, and issue tracking systems that are managed by, or on behalf of, the Licensor for the purpose of discussing and improving the Work, but excluding communication that is conspicuously marked or otherwise designated in writing by the copyright owner as "Not a Contribution."

"Contributor" shall mean Licensor and any individual or Legal Entity on behalf of whom a Contribution has been received by Licensor and subsequently incorporated within the Work.

- 2. Grant of Copyright License. Subject to the terms and conditions of this License, each Contributor hereby grants to You a perpetual, worldwide, non-exclusive, no-charge, royalty-free, irrevocable copyright license to reproduce, prepare Derivative Works of, publicly display, publicly perform, sublicense, and distribute the Work and such Derivative Works in Source or Object form.
- 3. Grant of Patent License. Subject to the terms and conditions of this License, each Contributor hereby grants to You a perpetual, worldwide, non-exclusive, no-charge, royalty-free, irrevocable (except as stated in this section) patent license to make, have made, use, offer to sell, sell, import, and otherwise transfer the Work, where such license applies only to those patent claims licensable by such Contributor that are necessarily infringed by their Contribution(s) alone or by combination of their Contribution(s) with the Work to which such Contribution(s) was submitted. If You institute patent litigation against any entity (including a cross-claim or counterclaim in a lawsuit) alleging that the Work or a Contributory patent infringement, then any patent licenses granted to You under this License for that Work shall terminate as of the date such litigation is filed.

- 4. Redistribution. You may reproduce and distribute copies of the Work or Derivative Works thereof in any medium, with or without modifications, and in Source or Object form, provided that You meet the following conditions:
  - (a) You must give any other recipients of the Work or Derivative Works a copy of this License; and
  - (b) You must cause any modified files to carry prominent notices stating that You changed the files; and
  - (c) You must retain, in the Source form of any Derivative Works that You distribute, all copyright, patent, trademark, and attribution notices from the Source form of the Work, excluding those notices that do not pertain to any part of the Derivative Works; and
  - (d) If the Work includes a "NOTICE" text file as part of its distribution, then any Derivative Works that You distribute must include a readable copy of the attribution notices contained within such NOTICE file, excluding those notices that do not pertain to any part of the Derivative Works, in at least one of the following places: within a NOTICE text file distributed as part of the Derivative Works; within the Source form or documentation, if provided along with the Derivative Works; or, within a display generated by the Derivative Works, if and wherever such third-party notices normally appear. The contents of the NOTICE file are for informational purposes only and do not modify the License. You may add Your own attribution notices within Derivative Works that You distribute, alongside or as an addendum to the NOTICE text from the Work, provided that such additional attribution notices cannot be construed as modifying the License.

You may add Your own copyright statement to Your modifications and may provide additional or different license terms and conditions for use, reproduction, or distribution of Your modifications, or for any such Derivative Works as a whole, provided Your use, reproduction, and distribution of the Work otherwise complies with the conditions stated in this License.

- 5. Submission of Contributions. Unless You explicitly state otherwise, any Contribution intentionally submitted for inclusion in the Work by You to the Licensor shall be under the terms and conditions of this License, without any additional terms or conditions. Notwithstanding the above, nothing herein shall supersede or modify the terms of any separate license agreement you may have executed with Licensor regarding such Contributions.
- 6. Trademarks. This License does not grant permission to use the trade names, trademarks, service marks, or product names of the Licensor, except as required for reasonable and customary use in describing the

origin of the Work and reproducing the content of the NOTICE file.

- 7. Disclaimer of Warranty. Unless required by applicable law or agreed to in writing, Licensor provides the Work (and each Contributor provides its Contributions) on an "AS IS" BASIS, WITHOUT WARRANTIES OR CONDITIONS OF ANY KIND, either express or implied, including, without limitation, any warranties or conditions of TITLE, NON-INFRINGEMENT, MERCHANTABILITY, or FITNESS FOR A PARTICULAR PURPOSE. You are solely responsible for determining the appropriateness of using or redistributing the Work and assume any risks associated with Your exercise of permissions under this License.
- 8. Limitation of Liability. In no event and under no legal theory, whether in tort (including negligence), contract, or otherwise, unless required by applicable law (such as deliberate and grossly negligent acts) or agreed to in writing, shall any Contributor be liable to You for damages, including any direct, indirect, special, incidental, or consequential damages of any character arising as a result of this License or out of the use or inability to use the Work (including but not limited to damages for loss of goodwill, work stoppage, computer failure or malfunction, or any and all other commercial damages or losses), even if such Contributor has been advised of the possibility of such damages.
- 9. Accepting Warranty or Additional Liability. While redistributing the Work or Derivative Works thereof, You may choose to offer, and charge a fee for, acceptance of support, warranty, indemnity, or other liability obligations and/or rights consistent with this License. However, in accepting such obligations, You may act only on Your own behalf and on Your sole responsibility, not on behalf of any other Contributor, and only if You agree to indemnify, defend, and hold each Contributor harmless for any liability incurred by, or claims asserted against, such Contributor by reason of your accepting any such warranty or additional liability.

END OF TERMS AND CONDITIONS

APPENDIX: How to apply the Apache License to your work.

To apply the Apache License to your work, attach the following boilerplate notice, with the fields enclosed by brackets "[]" replaced with your own identifying information. (Don't include the brackets!) The text should be enclosed in the appropriate comment syntax for the file format. We also recommend that a file or class name and description of purpose be included on the same "printed page" as the copyright notice for easier identification within third-party archives.

Copyright 2021-2022, World Meteorological Organization (WMO)

Licensed under the Apache License, Version 2.0 (the "License"); you may not use this file except in compliance with the License.

```
You may obtain a copy of the License at

http://www.apache.org/licenses/LICENSE-2.0

Unless required by applicable law or agreed to in writing, software

distributed under the License is distributed on an "AS IS" BASIS,

WITHOUT WARRANTIES OR CONDITIONS OF ANY KIND, either express or implied.

See the License for the specific language governing permissions and

limitations under the License.
```

## **11.2 Documentation**

The documentation is released under the Creative Commons Attribution 4.0 International (CC BY 4.0) license.

# TWELVE

## **INDICES AND TABLES**

- genindex
- modindex
- search